



Loud vehicle monitoring in four Dutch cities and mitigation options

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for UNECE GRBP Task Force Vehicle Sound



Overview



1. Introduction and causes
2. Monitoring loud vehicles in G4 cities
3. Approach and results
4. Causes of high noise and observations
5. Potential mitigation options and policies
6. EU project LENS
7. Characteristic driving conditions
8. Vehicle modifications
9. Feasibility of noise cameras
10. Conclusions and follow-up
11. Some suggestions

Introduction

- Loud vehicles lead to many complaints and significant impact on residents along affected routes both in urban and rural areas
- Local communities and associations protesting and petitioning
- The high noise levels have minor effect on long term Lden average exposure levels
- Technical and policy solutions sought
- Monitoring of loud vehicles in four NL cities (G4)
- EU project LENS on mitigation of L-vehicle noise and emissions
- Study on feasibility of noise cameras



G4 Cooperation

- City cooperation on how to tackle the issue of loud vehicles and lobby to NL Ministries
- Lack of police capacity for enforcement – few options for cities
- High serious annoyance rate for loud vehicles (10-19%)
- TNO contracted to perform roadside measurements in Amsterdam, Rotterdam, The Hague and Utrecht
- **Aim: to investigate causes of high noise levels and potential mitigation measures**
(Not to develop a noise camera)



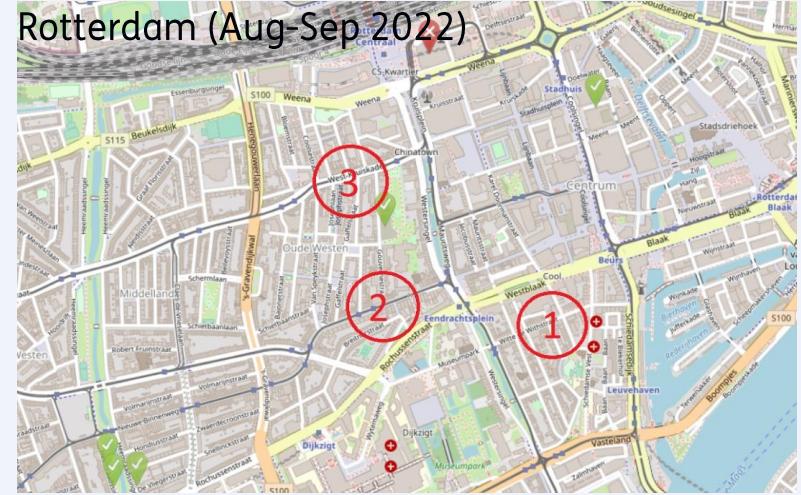
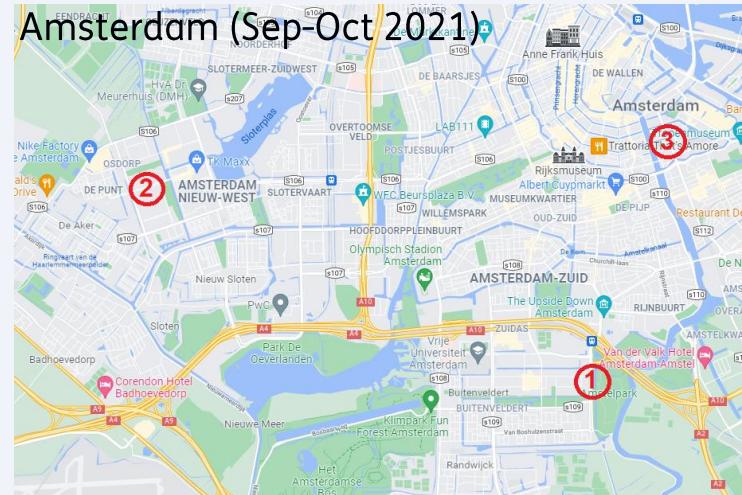
Causes of increased noise impact

- More vehicles on the road
- Higher building density and noise sensitivity
- Low enforcement of vehicle noise
- Vehicle power has increased
- Driving behaviour
- Vehicle modifications: tuning methods, products and services to increase power and noise are widespread
- New vehicles are not necessarily quieter than previous models in practice



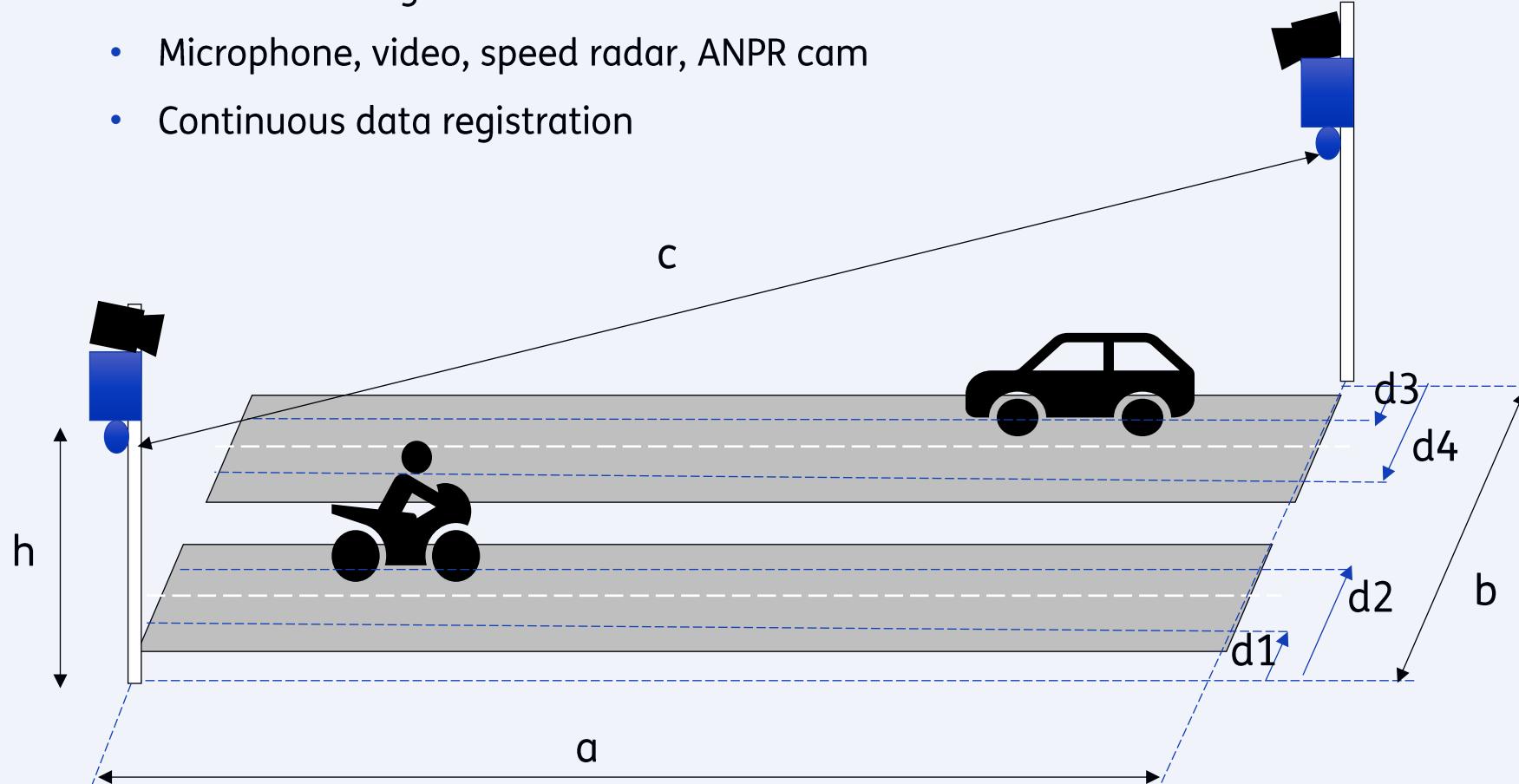
Monitoring of loud vehicles in the G4 cities

- 3 locations per city,
5-7 days per location
- Mostly 50 km/h through roads,
2x1 or 2x2 lanes
- Noise measurement with video and
numberplate camera (ANPR) for
vehicle identification
- Cars, motorcycles, mopeds/scooters,
quads and trikes
- Objective: features of loud vehicles
and sound levels per location, aimed
at causes and measures

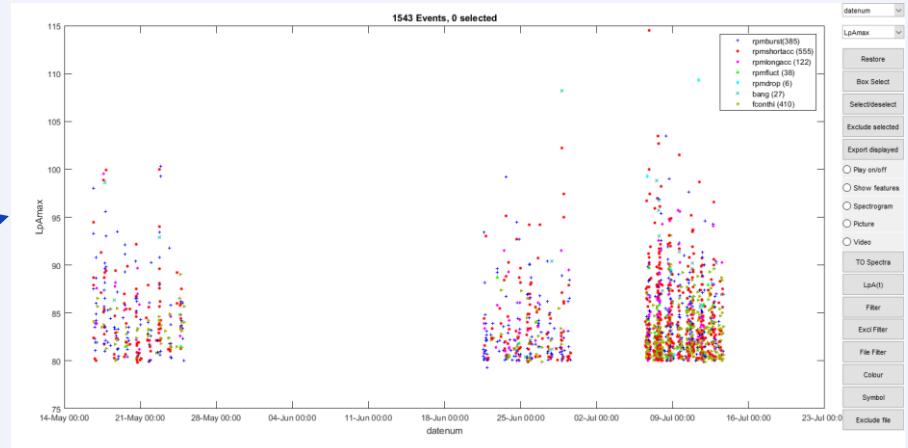
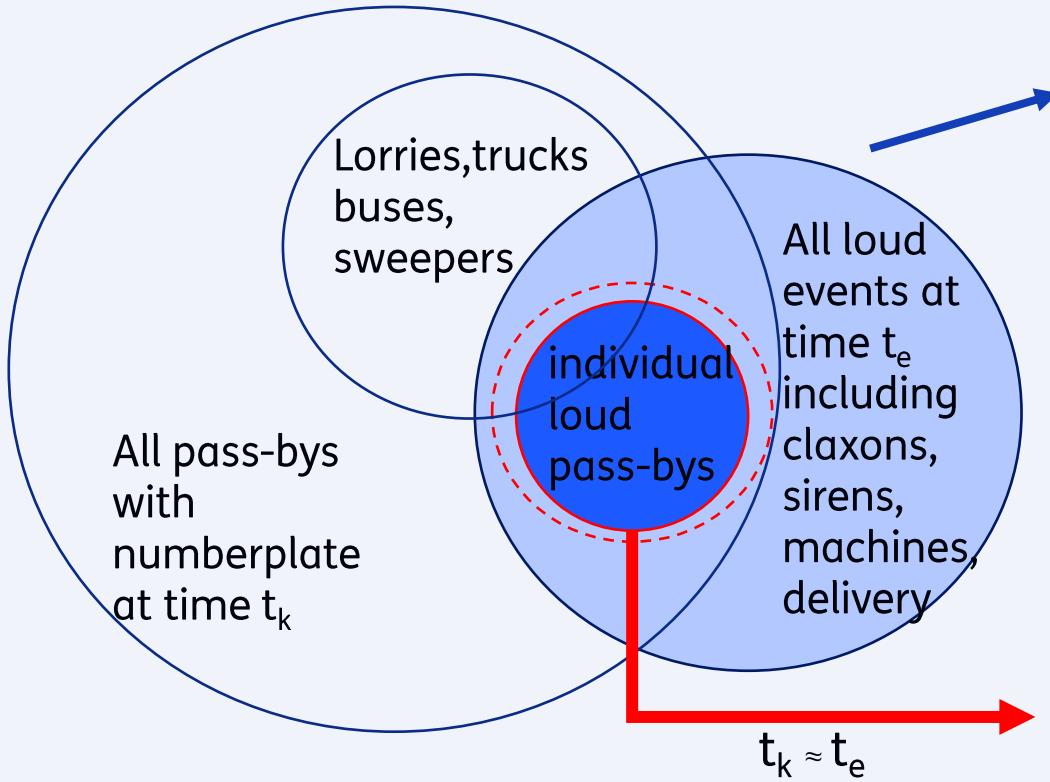


Measurement setup

- One monitoring unit on each side of the road
- Microphone, video, speed radar, ANPR cam
- Continuous data registration

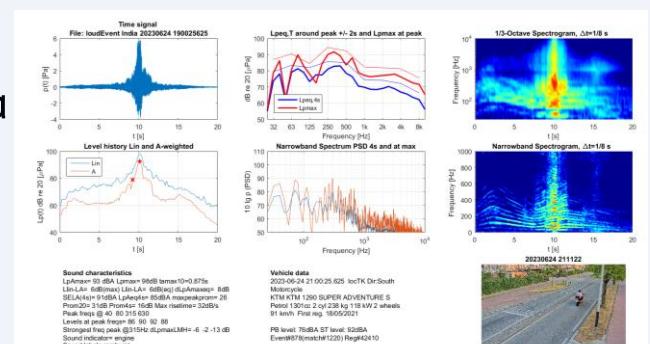


Selection process – from thousands to hundreds



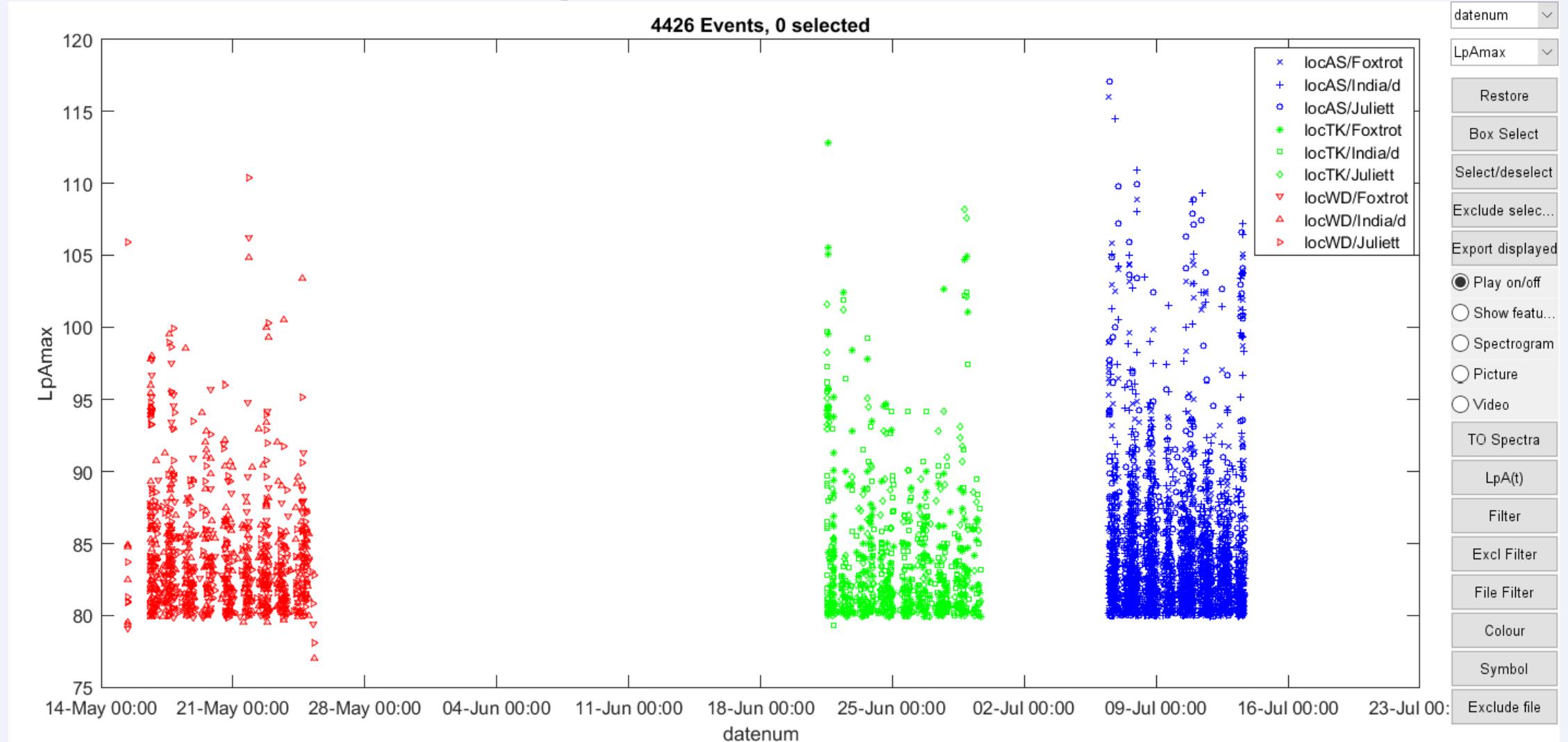
Event browser for detecting vehicle vs. non-vehicle sources and sound characteristics

Numberplate → vehicle data
Sound level and acoustic features
Video and image
Only cars, motorcycles, mopeds, trikes and quads

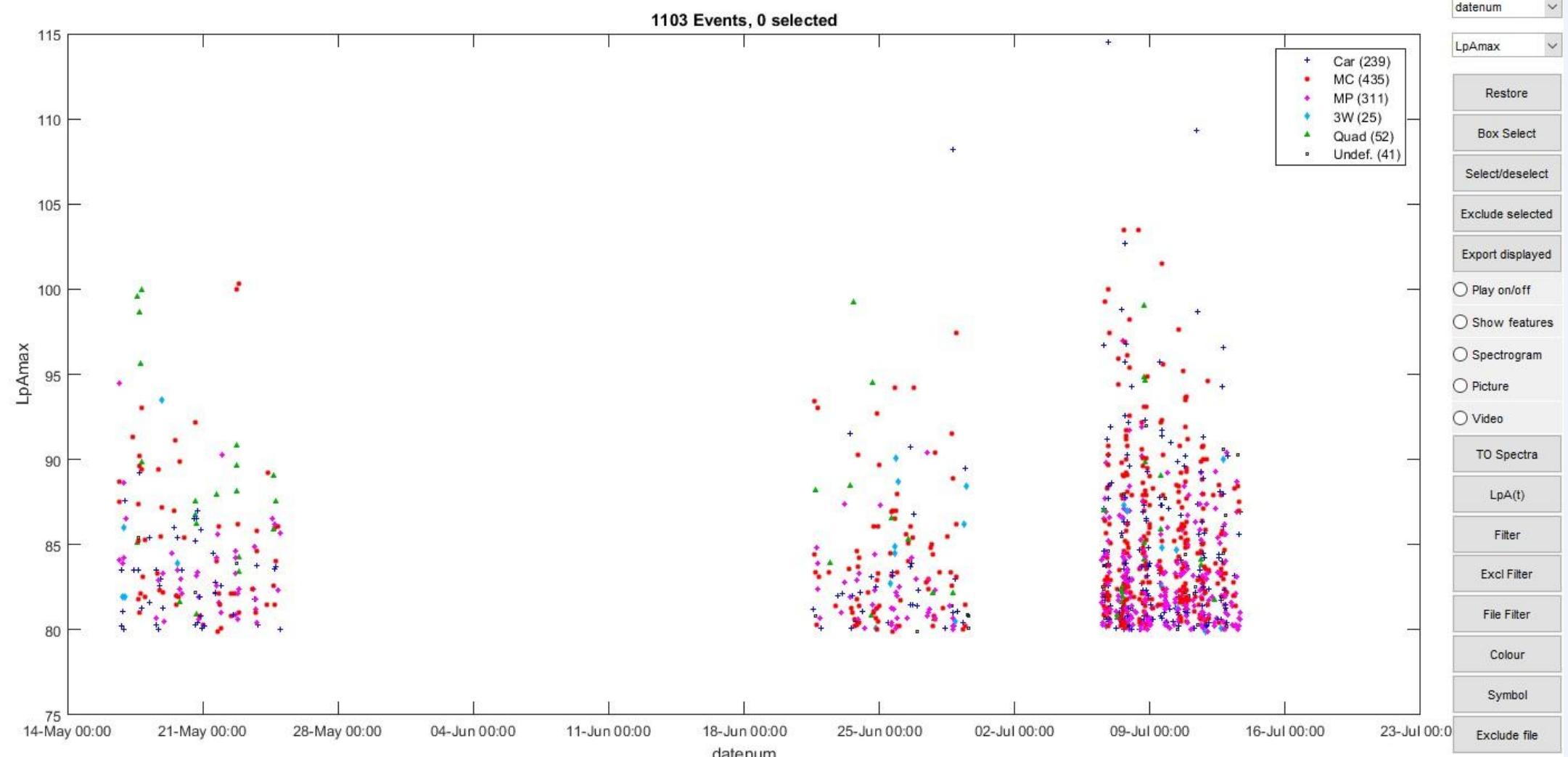


Feature and vehicle data overview

Event browser – L_{pAFmax} all events > 80 dB(A), Utrecht



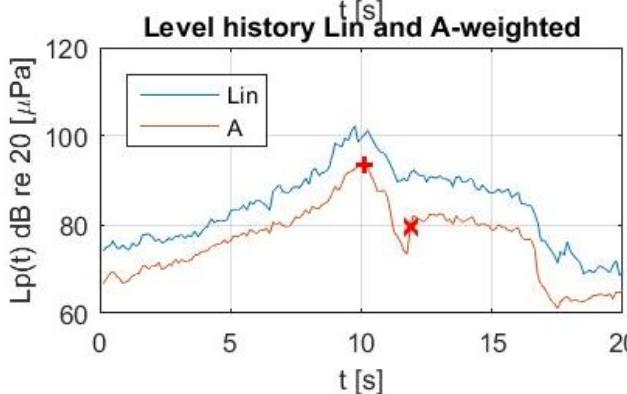
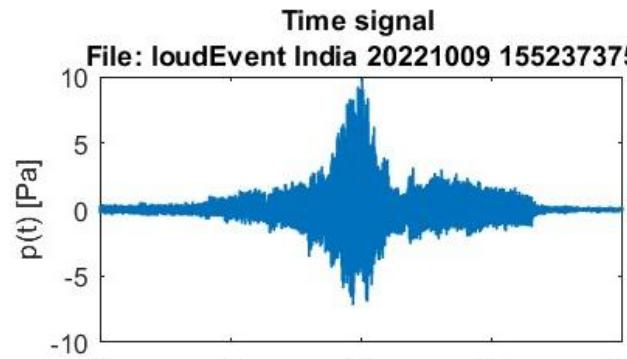
Event browser – selected loud vehicles, Utrecht



Sound features for each event

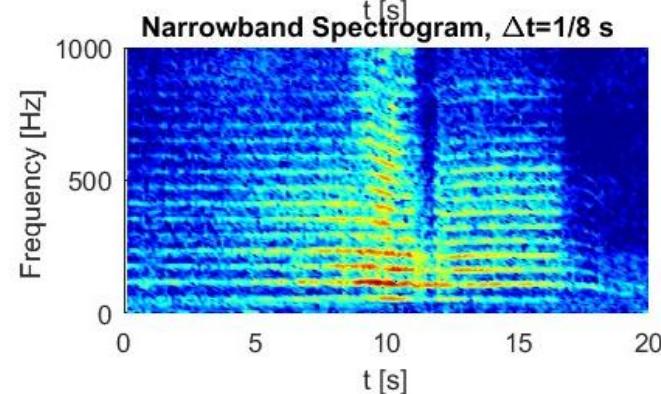
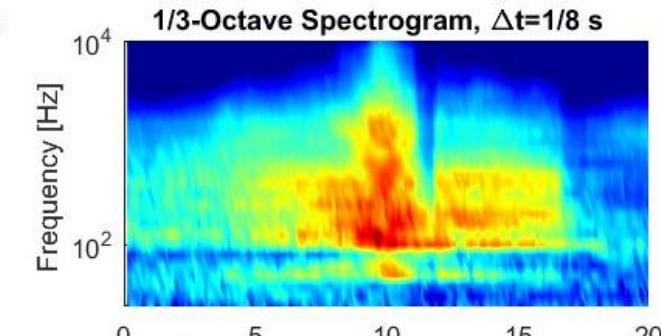
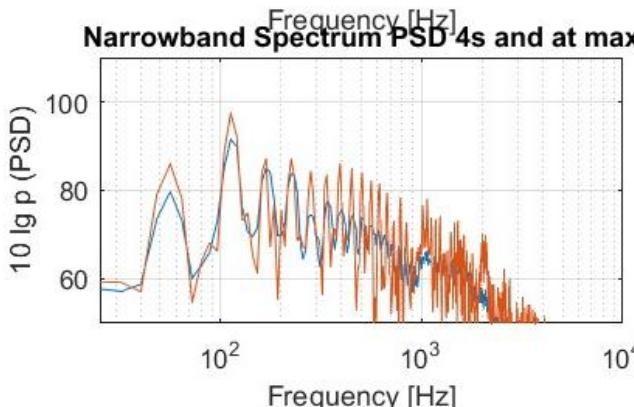
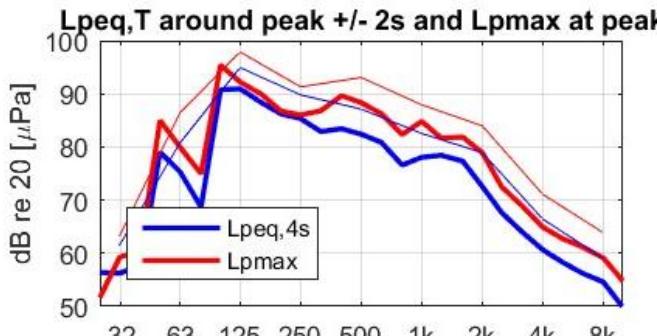
- Single value parameters:
 - L_{pAFmax} and L_{pFmax} , $L_{pAeq,4s}$ and $L_{peq,4s}$
 - Normalised low, medium and high frequency levels, defined as $L_{pFmax}(\text{total}) - L_{pFmax}(\text{frange})$ with frange = 20-250 Hz, 250-1000 Hz and 1000-10000 Hz
 - $L_{pAFmax} - L_{pAeq,4s}$, $L_{pFmax} - L_{pFmax}$
 - Strongest frequency f_1 and spectrum amplitude $L_p(f_1)$
 - Number of narrowband harmonics, especially for engine noise
 - Rise time of the noise level history ($dL/dt)_{\text{max}}$
 - Text labels indicative of sound content, such as 'impact', 'siren', 'claxon', 'engine', 'repet', 'fcontlo', 'fconthi', 'voice' (specific algorithms)
 - Text labels for engine speed related sound content (specific algorithms)
 - And many others
- Array parameters:
Time signal, level history, third octave spectrum and spectrogram, narrowband spectrum and spectrogram

Sound features – High rpm moped 93 dB(A)



Sound characteristics

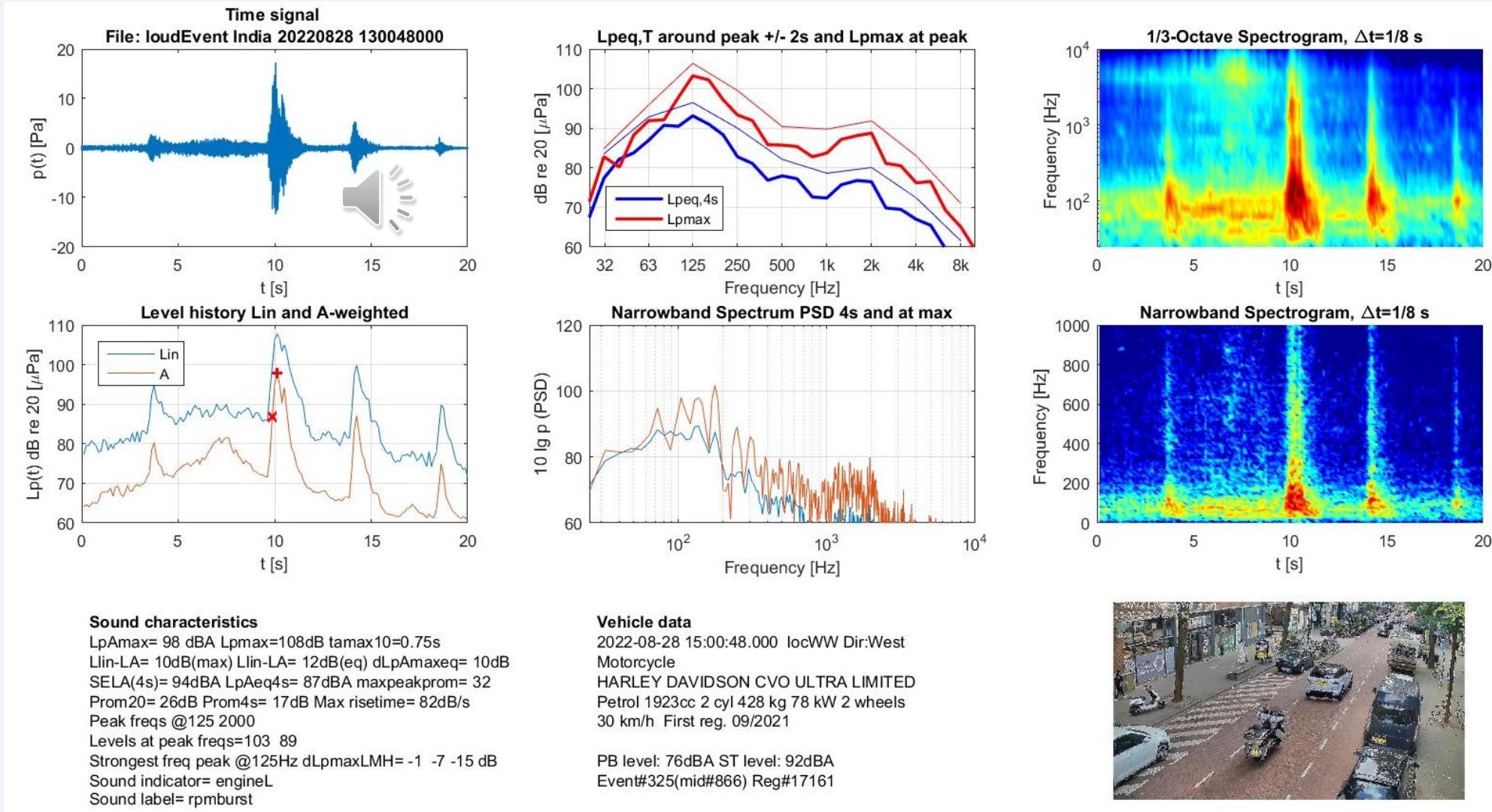
$L_pA_{max} = 93$ dB(A) $L_pmax = 102$ dB tamax=10=3s
 $L_{lin-LA} = 9$ dB(max) $L_{lin-LA} = 8$ dB(eq) $dL_pA_{maxeq} = 5$ dB
 $SELA(4s) = 95$ dB(A) $L_pAeq4s = 89$ dB(A) maxpeakprom= 4
 Prom20= 19dB Prom4s= 12dB Max risetime= 50dB/s
 Peak freqs @ 50 400
 Levels at peak freqs= 85 90
 Strongest freq peak @400Hz $dL_pmaxLMH = -4 -6 -18$ dB
 Sound indicator= engineL fcontlo
 Sound label= fconthi



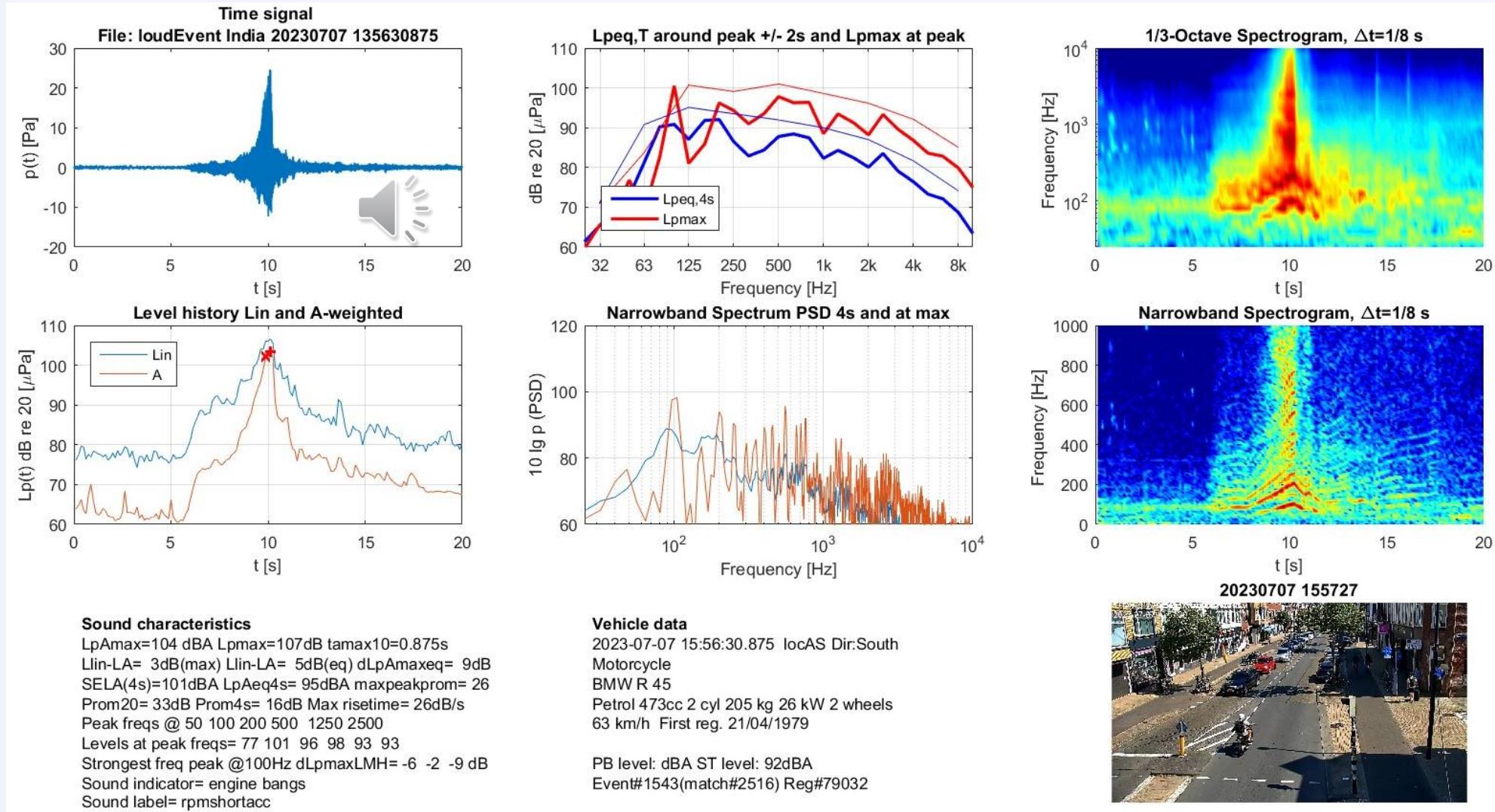
Vehicle data

2022-10-09 17:52:37.375 locAL Dir:North
 Moped
 HANWAY RAW 50
 Petrol 49cc 1 cyl 96 kg 2.2 kW 2 wheels
 48 km/h First reg. 30/07/2016
 PB level: 69dB(A) ST level: 80dB(A)
 Event#324(mid#746) Reg#81311

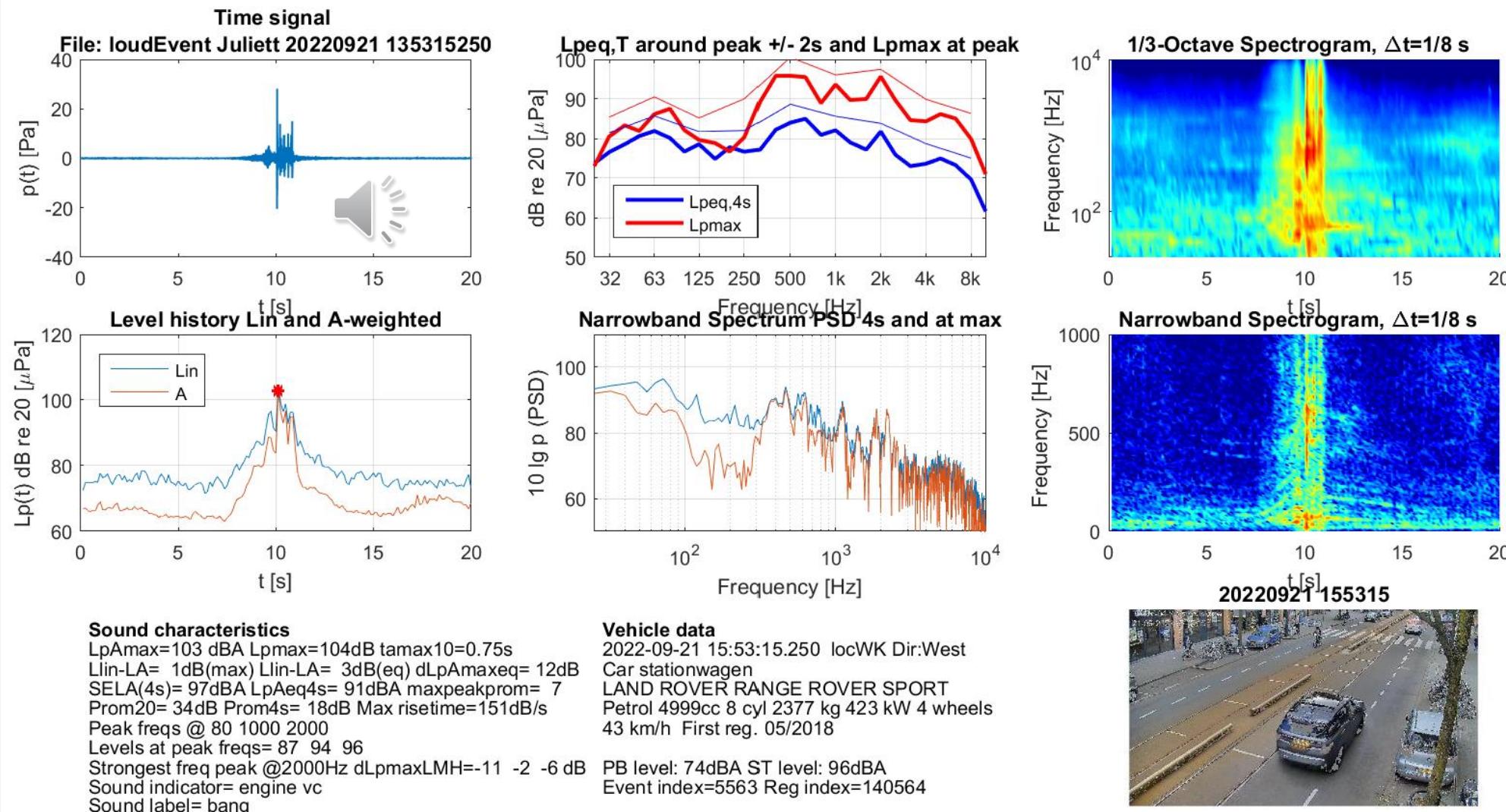
Sound features – Revving motorcycle 98 dB(A)



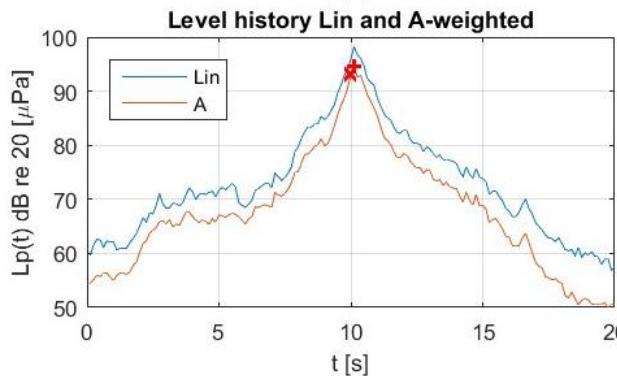
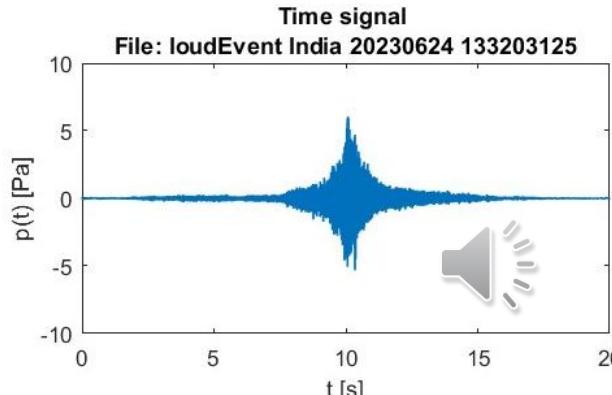
Sound features – Fast accelerating motorcycle 104 dB(A)



Sound features – Car with backfire noise 103 dB(A)

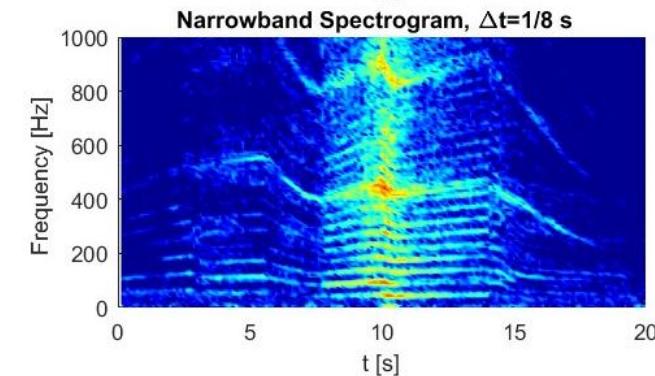
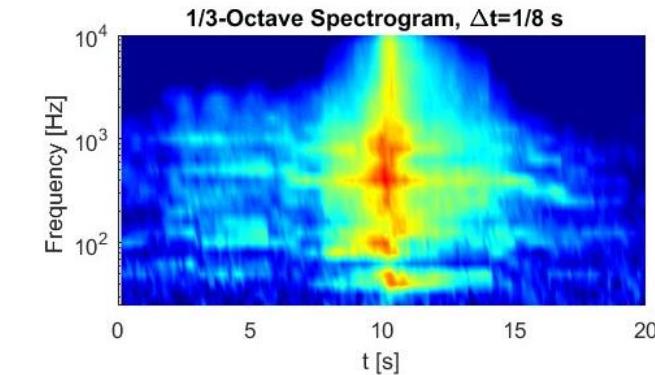
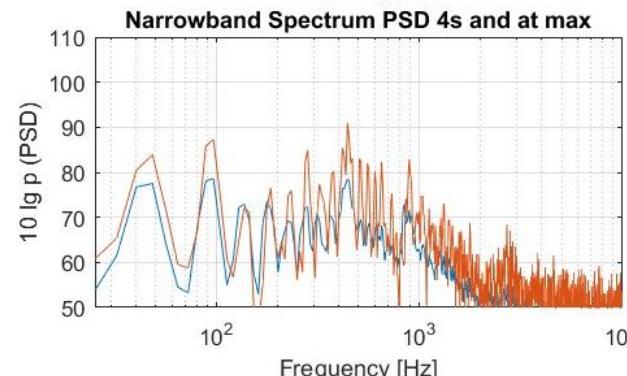
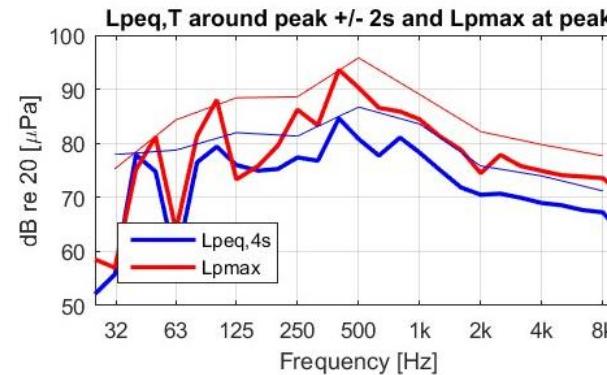


Sound features- Quad accelerating 95 dB(A)



Sound characteristics

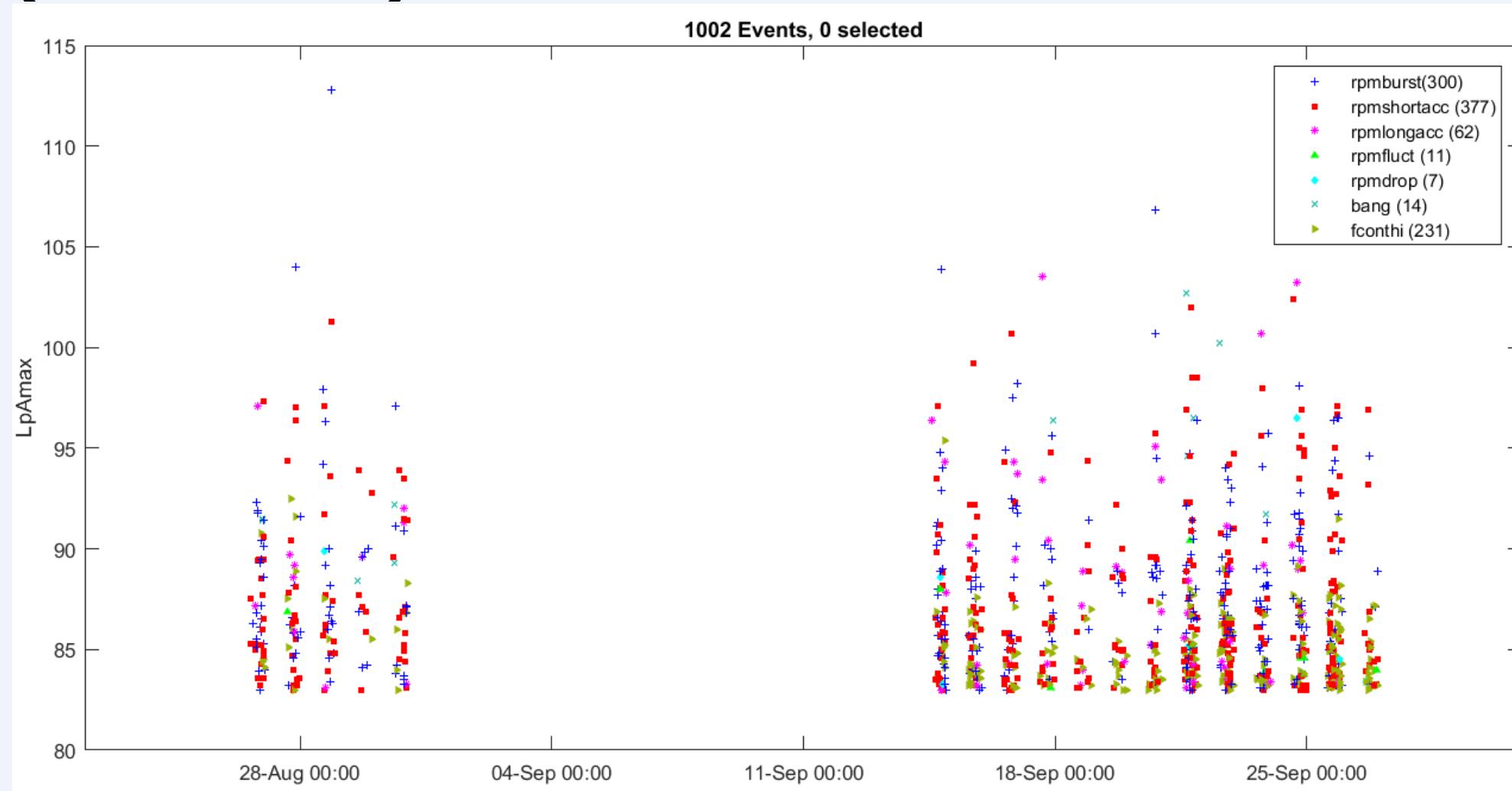
$LpAmax= 95$ dBA $Lpmax= 98$ dB $tamax10=1.625$ s
 $Llin-LA= 4$ dB(max) $Llin-LA= 4$ dB(eq) $dLpAmaxeq= 7$ dB
 $SELA(4s)= 93$ dBA $LpAeq4s= 87$ dBA $maxpeakprom= 23$
 $Prom20= 31$ dB $Prom4s= 15$ dB $Max risetime= 21$ dB/s
 Peak freqs @ 50 100 400 2500
 Levels at peak freqs= 81 88 94 78
 Strongest freq peak @400Hz $dLpmaxLMH= -8 -1 -13$ dB
 Sound indicator= engine
 Sound label= rpmburst



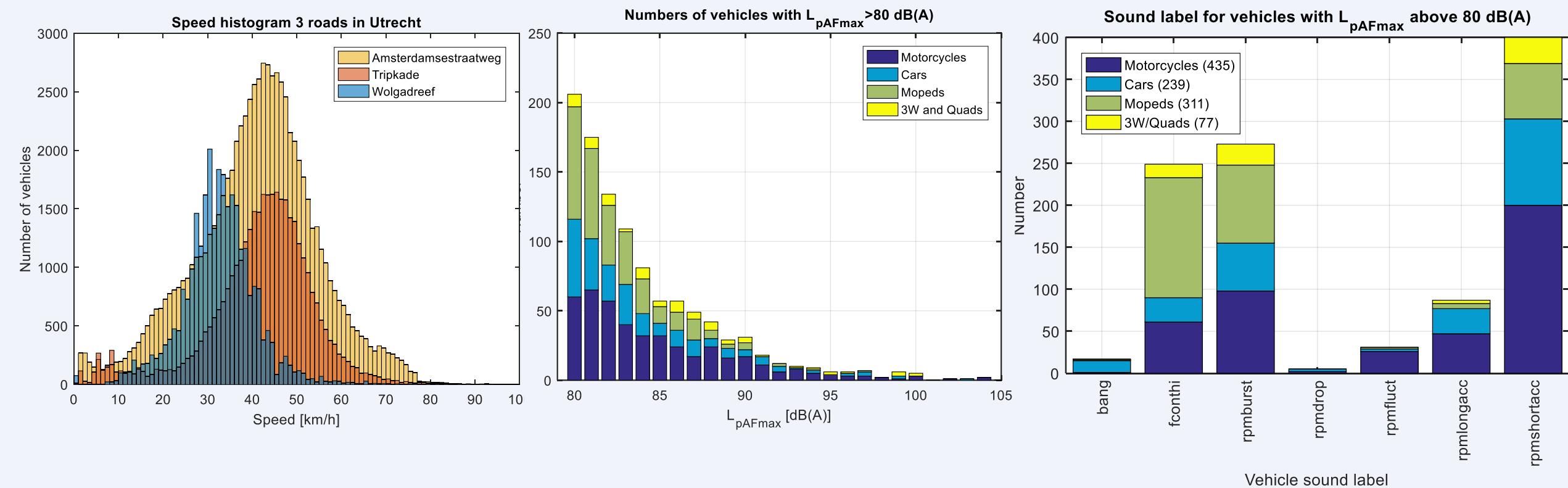
20230624 153333



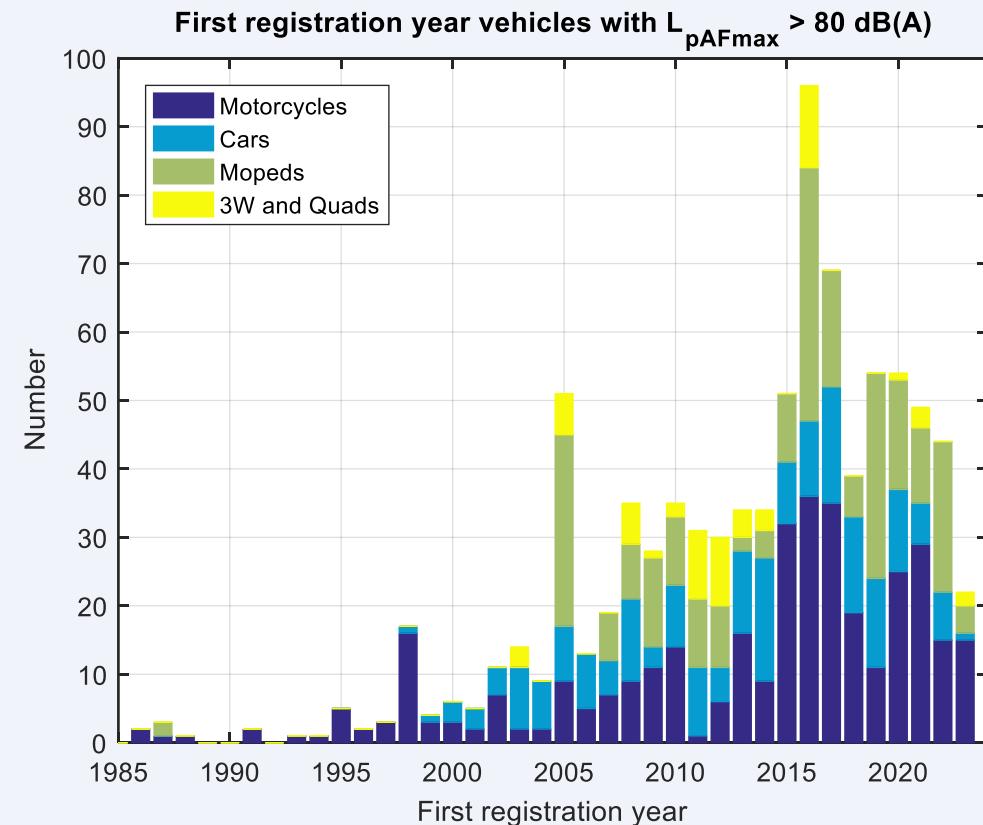
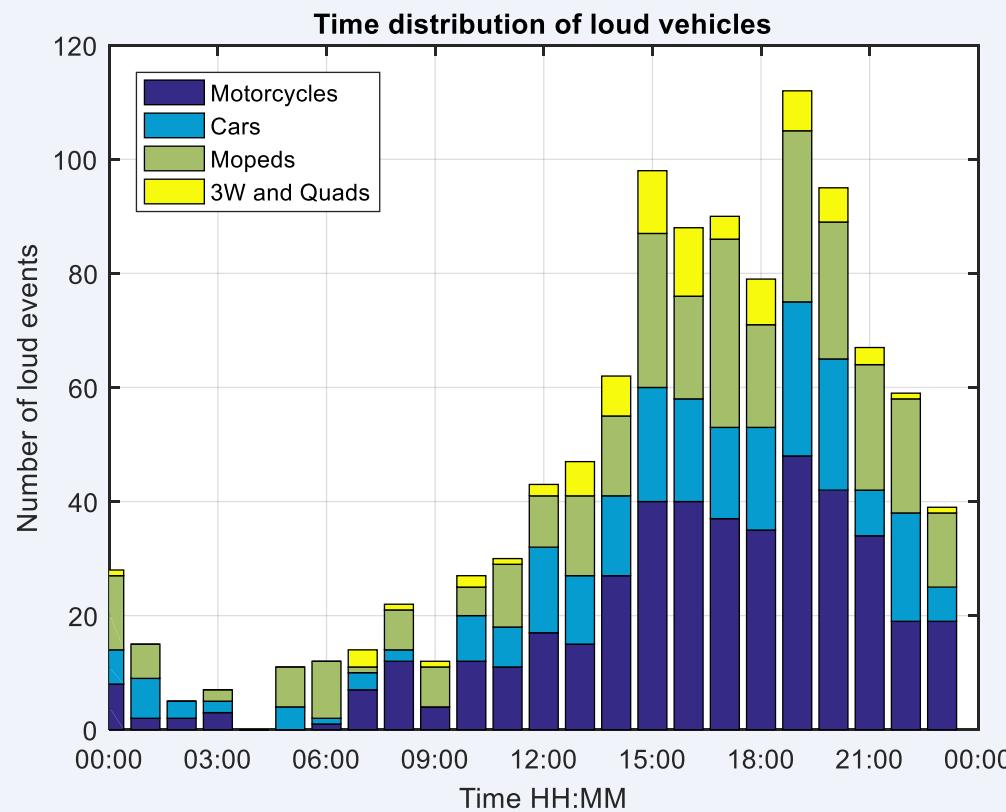
Event browser - sound features of loud vehicles (Rotterdam)



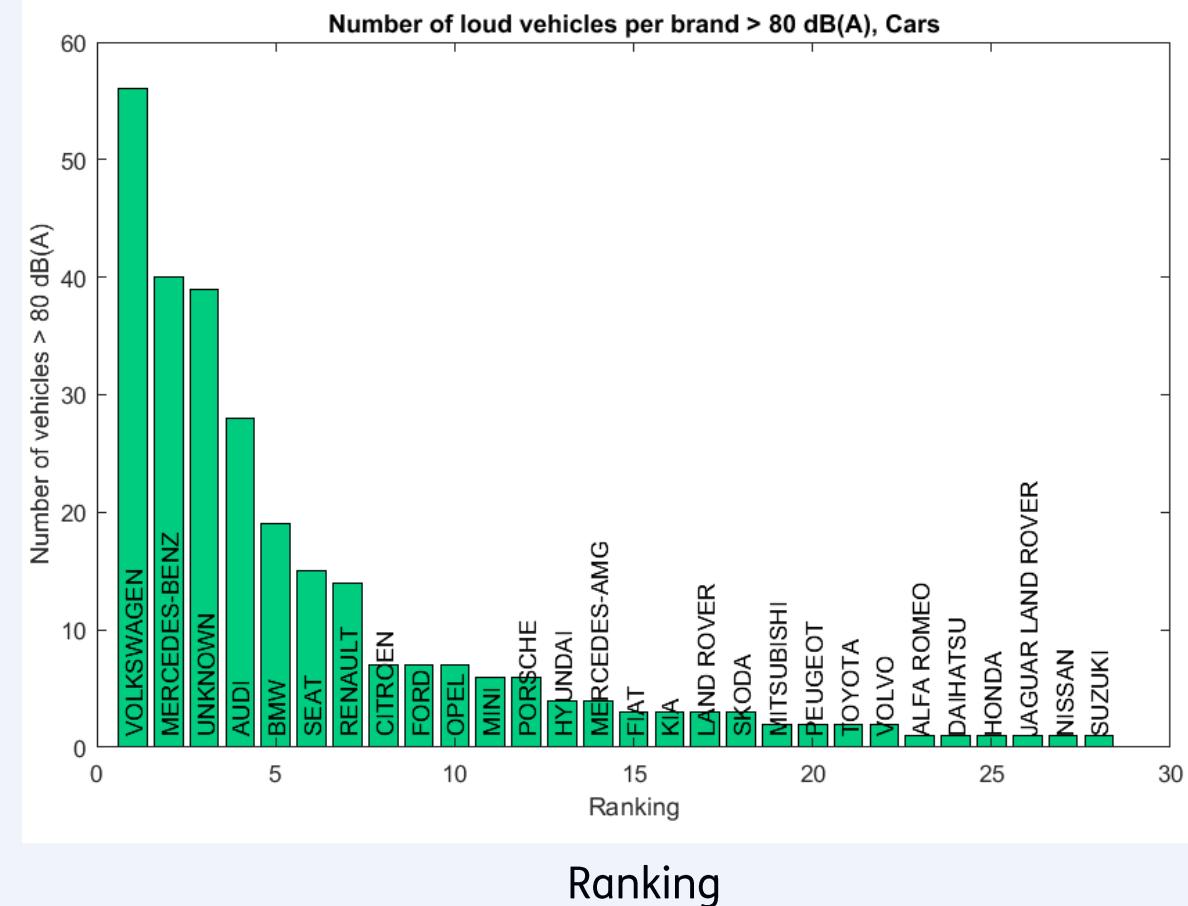
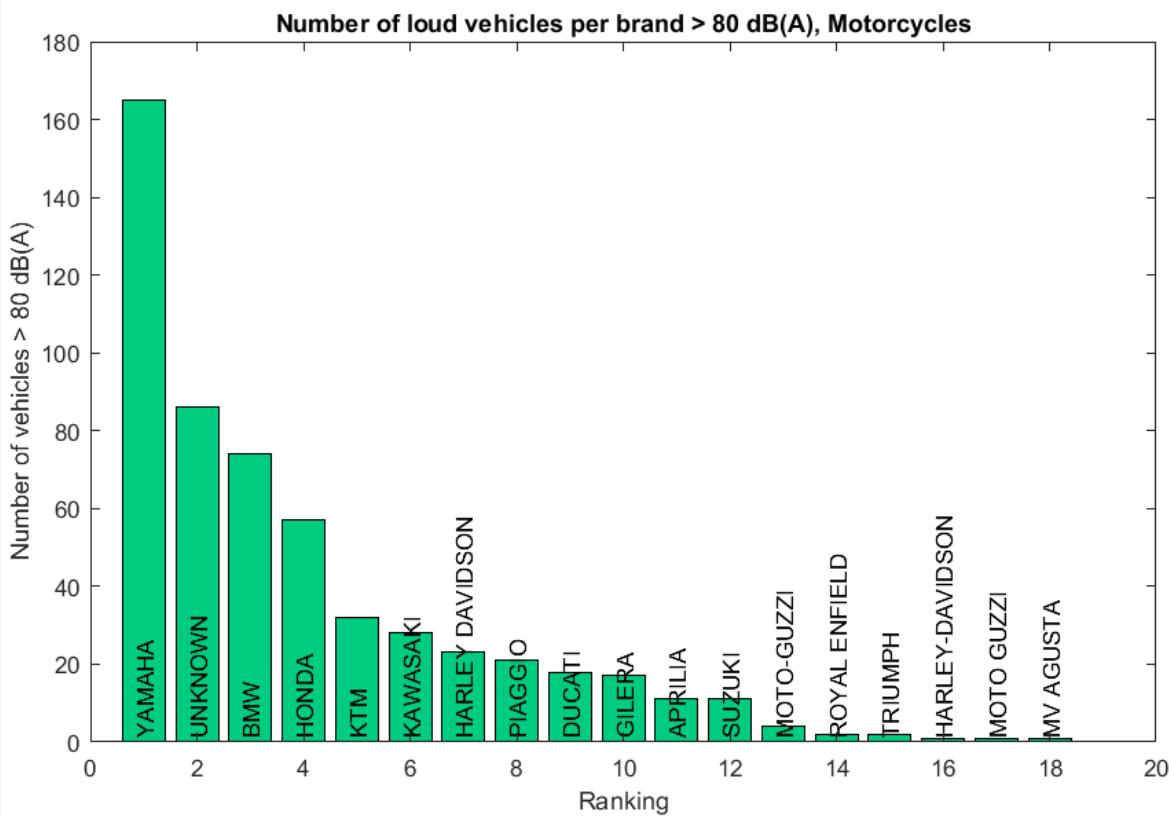
Speeds, numbers of loud vehicles, vehicle sound labels Utrecht



Time distribution and age of loud vehicles, Utrecht



Ranking of makes, motorcycles and cars, Utrecht



Causes of high noise levels

- Driving behaviour, vehicle modifications or both
 - Driving behaviour: engine revving, fast acceleration, late gear change, speeding, backfire
 - Some new vehicles intrinsically loud ‘sports mode’ etc.
 - Vehicle modifications: tuning, boosting (turbo, supercharger etc.)
 - Partly detectable from sound
- 

Components	Modification	Effect on noise	Effect on power
Electronic control unit (ECU)	Reprogramming or replacing		
	Boost power	Increase at higher torque or rpm	Increase
	Modify injection, timing or quantity	Increase and/or backfire in the exhaust	Increase
	Electronic derestriction	Increase at high rpm	
Mechanical derestriction	Derestriction set	Increase at high rpm	Increase
Air intake + and silencer	Widening, replacement or removal	Increase	Increase
Catalyst	Removal	Increase	Increase
Exhaust	Removal	Increase	Increase
Exhaust	Replace by non-compliant exhaust	Increase	Possible Increase
Exhaust	Replace by compliant louder exhaust	Increase	
Exhaust	Drill holes	Increase	
Exhaust	Damage or remove internal parts	Increase	
Motor	Modify intake or exhaust ports	Increase	
	Change compression	Increase	
	Change stroke, bore or cylinder volume	Increase	
	Change injection system or camshaft	Increase	
Transmission	Transmission ratio change	Increase	

Observations

- Many speeding vehicles
- High noise levels also at low speeds
- Motorcycles are loudest
- Show behaviour (backfire etc.)
- Particular brands are frequent
- Luxury sports cars but also smaller tampered vehicles
- Routes to recreational destinations (beaches, entertainment etc.), Café streets
Long straight city roads, loud acceleration after crossings
- Some locations many loud quads (rental?)
- Canyon streets and high rise flats –reflections
- The busier the road and more complex the situation, the harder it is to correctly identify vehicles



Mitigation measures

- Measures matrix developed in 2020 (TNO report for Dutch Ministry)
- G4: General and location-specific measures, such as:
 - Speed limit down to 30 km/h where possible
 - Warning sign for drivers, static or electronic
 - Access restrictions for vehicle types or individual
 - More, improved or automatic enforcement (e.g. noise camera)
 - Targeted enforcement based on hot spots and times
 - Attended enforcement based on Regulation RVV Article 57, audible indications of too loud vehicles:
 - - heard from afar
 - - exhaust pops and bangs
 - - unnecessary and loud engine revving
 - - unnecessary and loud acceleration
 - - speeding
 - - visible modifications such as missing dB killer, small exhaust etc.



Policy progress

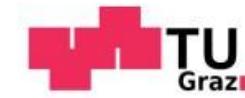
- November 2022 G4 memorandum
 - *Simpler enforcement process for the Police*
 - *Use of noise measurements for communication and enforcement*
 - *Communication to drivers*
- TNO report 2020 Policy options for noise of motorised two-wheelers (Tweede kamer/Parliament)
- RDW investigation on options 2022 (for Dutch parliament)
 - *Use of existing technical inspections*
 - *Improvement of regular enforcement by the police*
 - *other aspects*
- Review of enforcement options by Rotterdam en Amsterdam municipalities
- Warning signs for noise introduced by Rotterdam en Amsterdam 2023
- Police checks and fines in Rotterdam and the Hague
- TNO study on feasibility of noise camera in NL 2023/2024
- Sorama noise camera tests in Amsterdam 2024

EU project LENS

- L-vehicles Emissions and Noise mitigation Solutions
motorcycles/mopeds/scooters/trikes/quads
2022-2025
- Relevant driving conditions for highest exhaust emissions and noise
- Development of on board measurement systems for L-vehicles
- Research, detection and approach for tampering
- Measurement programme for 150 L-vehicles – on board and pass-by measurements for emissions and noise
- Impact analysis of noise and emissions
- Proposals for mitigation measures and improved testing methods



Funded by
the European Union



Vehicle categorisation	Typical Photos of Models		Key specifications
L1e-A Powered cycle			≤50 cc (P1), ≤25 km/h, ≤1 kW
L1e-B Two-wheel moped			≤50 cc (P1), ≤45 km/h, ≤4 kW
L2e Three-wheel moped			≤50 cc (P1) / ≤500 cc (C1), ≤45 km/h, <4 kW, ≤270 kg
L3e Two-wheel motorcycle			A1: ≤125 cc, ≤11 kW, ≤0.1 kW/kg A2: ≤35 kW, ≤0.2 kW/kg A3: >35 kW, >0.2 kW/kg
L4e Two-wheel motorcycle with side-car			Equivalent to the corresponding L3e
L5e-A Tricycle			3 wheels, ≤1000 kg, max 5 seats
L5e-B Commercial tricycle			3 wheels, ≤1000 kg, max 2 seats, loading volume ≥ 0.6m³
L6e-A Light on-road quad			≤50 cc (P1) / ≤500 cc (C1), ≤45 km/h, ≤4 kW, ≤425 kg
L6e-B Light quadri-mobile			≤50 cc (P1) / ≤500 cc (C1), ≤45 km/h, ≤6 kW, ≤425 kg
L7e-A Heavy on-road quad			≤15 kW, ≤450 kg
L7e-B Heavy all terrain quad			B1: ≤90 km/h, ≤450 kg B2: ≤15 kW, ≤450 kg
L7e-C Heavy quadri-mobile			CU: ≤90 km/h, ≤15 kW, ≤600 kg CP: ≤90 km/h, ≤15 kW, ≤450 kg

L-vehicles

LENS: Common driving conditions of loud vehicles

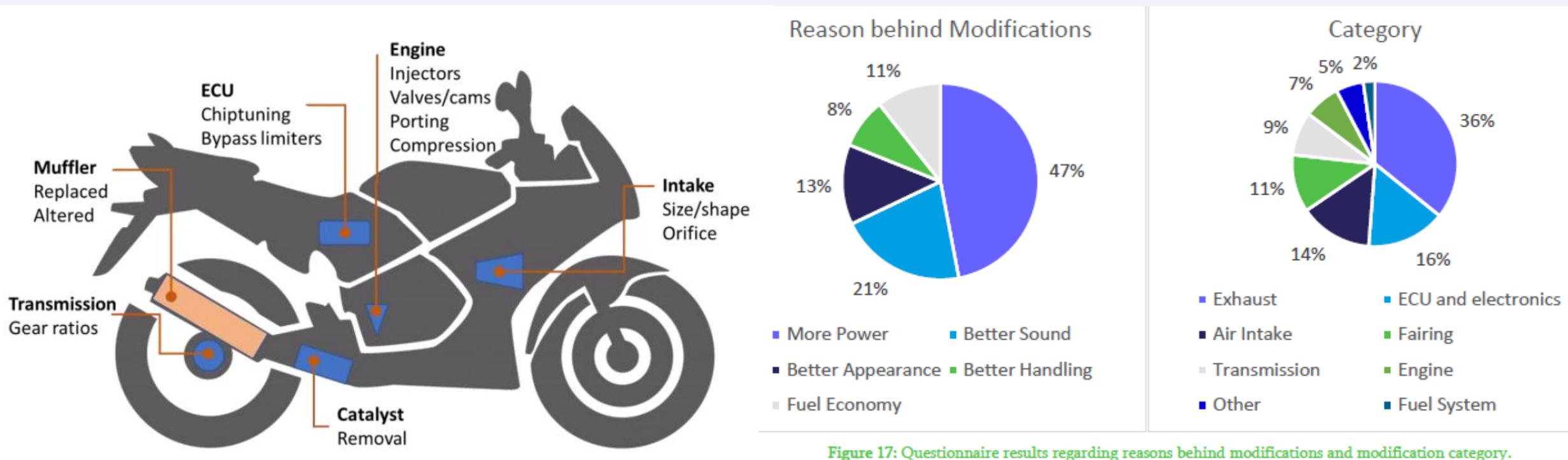
- Recommendations for driving conditions in LENS test programme
- Producing the highest exhaust emissions and noise levels

Condition	Vehicle operation	Short name	Already in noise TA?	Remarks
(1) Cold start (mainly for emissions)	Engine start	'coldstart'	No	
(2) rpm burst	Stationary, short activation and release of accelerator	'rpmburst'	No	From idling, 3x 50% max rpm
(3) Acceleration from standstill, G1, G2 Loaded + unloaded	Acceleration, late gear change	'rpmlongacc'	No	
(4) Max rpm passby esp. mopeds, scooters, sports MCs	Constant speed with max rpm	'rpmconti'	No	
(5) Transition from constant speed or acceleration phases to deceleration phases	Deceleration	'rpmdropoff'	No	
(6) 'Max' acceleration from standstill, G1, G2	Acceleration	'rpmshortacc'	No	
(7) Acceleration at speed, from 50 to 100 kmh	Acceleration, may be varied	'rpmmidspeedacc'	MC: ASEP no, RD-ASEP yes	
(8) rpm fluctuation	Variable speed	'rpmfluct'	No	Accelerator intermittent
(9) Backfire (occurrence, distance not critical)	Multiple gear changing or manual operation	'bang'	No for R41.04. R41.05 measurement covers deceleration phase	Condition at which backfire would be most likely

Source: LENS report D6.1,
TNO, Emisia/HSDAC, IFPEN

LENS: Vehicle modifications/ tampering

- Europe-wide survey on most common vehicle modifications and reasons



Source: LENS report D5.1, Emisia, TNO

Feasibility of noise cameras in the Netherlands

- TNO Study for NL cities and Ministry, 2024
- Review of required functionality and requirements
- Consultation of stakeholders (suppliers, authorities et al)
- Review of available systems and pilot tests
- Legal aspects
- Recommendations



Warning systems, Munisense (NL)



Sorama (NL)



dBFlash (FR)



Hydra/Bruitparif (FR)



SoundVue (UK)



Feasibility of noise cameras: Findings

- Systems are available, not yet certified, require pilot projects for evaluation
- Evaluations underway in several countries (FR,CH,UK,US,DE,BE at al)
- Analogy with speed cameras, also for enforcement process
- (semi) Mobile systems would be preferable
- 100% hit rate not probable, but allow rejection of false positives
Manual checks for penalties
- Technical challenges: complex situation with heavy traffic
- Legal:
 - Application for penalties is most demanding
 - Some changes required to legislation to incorporate noise cameras
 - Certification required, mainly for vehicle noise location
 - Data privacy is important but can be fulfilled
 - Threshold peak sound level is simplest criterium, depends on definition and road/traffic situation
 - Tampering detection partly possible for some types (backfire, loud exhaust),
but more complex to administer
- Benefits should be evident: reduced police effort and increased effectiveness

Conclusions and outlook

- Loud vehicle monitoring in the G4 cities provided insight into causes and potential mitigation measures
- Loudest vehicles are motorcycles, quads and three-wheelers, cars and mopeds
- Key causes are driving behaviour and vehicle modifications
- Overview of mitigation measures including roads, vehicles, drivers and enforcement
- From city monitoring and the LENS project:
Main driving conditions for loud vehicles identified, some easy to detect
- LENS: Insight into vehicle modifications, detection methods for tampering, mitigation solutions and impact analysis
- Feasibility of noise cameras in NL:
Possible, but legislation changes, certification, pilot projects and process integration required



Some suggestions

- International cooperation on technology and regulatory framework for vehicle noise enforcement including noise cameras
- Visual and sound criteria for roadside and PTI inspection related to noise, tampering detection and vehicle condition
- Implementation in apps
- Information exchange on enforcement practice for both police and vehicle authorities
- Roles of R&D, UNECE Regulations, EU regulations
- ??

With thanks to:

- Carlo Schoonebeek, City of Amsterdam
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- Adrienne Kuijer, City of The Hague
- Reinier Balkema, City of Utrecht
- Bart Stolte, NL Ministry of Infrastructure and Water management
- LENS Consortium
www.lens-horizoneurope.eu
- TNO colleagues for their contributions
Frans Staats, Elisabeth van Pruisen, Nikol Gulgelmovic,
Thomas Frateur, Pim van Mensch, Iddo Riemersma, Pierre Paschinger

- **Thank you for your attention!**



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Resources

- Policy options for reducing noise annoyance due to motorcycles, mopeds and scooters (In Dutch)
TNO Report TNO 2020 R11995, December 2020.
<https://www.tweedekamer.nl/downloads/document?id=2023D11440>
- TNO reports on city monitoring of loud vehicles (in Dutch) 2022-2023:
<https://publications.tno.nl/publication/34639225/HQhJBv/TNO-2022-R10053.pdf>
<https://publications.tno.nl/publication/34642304/5LYbE/TNO-2023-R10157b.pdf>
<https://publications.tno.nl/publication/34642306/jfWTon/TNO-2023-R10459.pdf>
<https://publications.tno.nl/publication/34642155/dn5zpu/TNO-2023-R12599.pdf>
- Noise camera feasibility study (in Dutch), TNO report 2024.
<https://publications.tno.nl/publication/34642766/7vId7Dyt/TNO-2024-R10444.pdf>
- Internoise article on loud vehicle monitoring (Proceedings Internoise 2024, Nantes)
https://doi.org/10.3397/IN_2024_3652
- LENS project website: www.lens-horizoneurope.eu (including deliverable reports)