



# Roadside measurements of L-vehicle emissions

Hafiz Hashim Imtiaz

Graz University of Technology



This project has received funding from the European Union's Horizon Europe research and innovation programme under grant agreement No 101056777

**LONS** L-vehicles Emissions and Noise mitigation Solutions

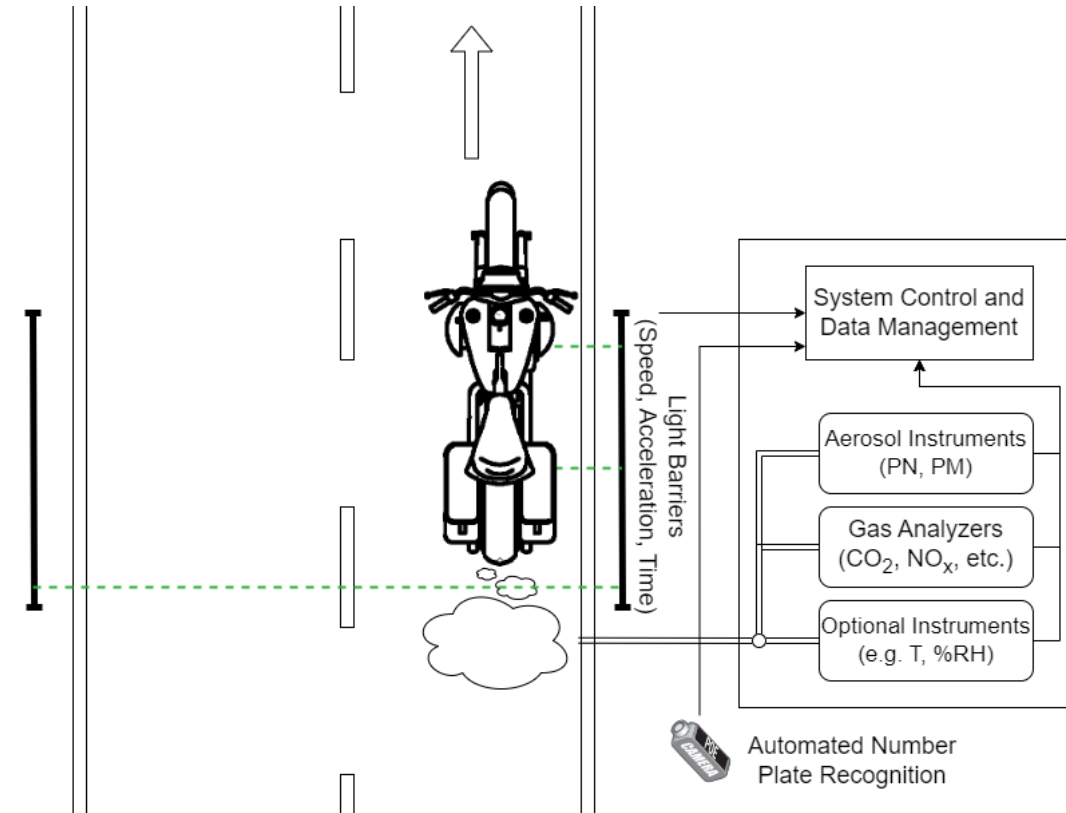
# Contents

- Roadside Emission Measurements
  - Setup
  - Device Validation
  - Data Management
  - Data Analysis
  - Schlieren Imaging of Vehicle Exhaust Plumes



# Roadside Emission Measurement by Point Sampling (PS)

- Sample extraction via tube, analyzers in PS bus
- Vehicle detection, speed and acceleration measurement via light barriers
- AI-based Automated Number Plate Recognition
- Logging vast amounts of data
- Battery powered operation





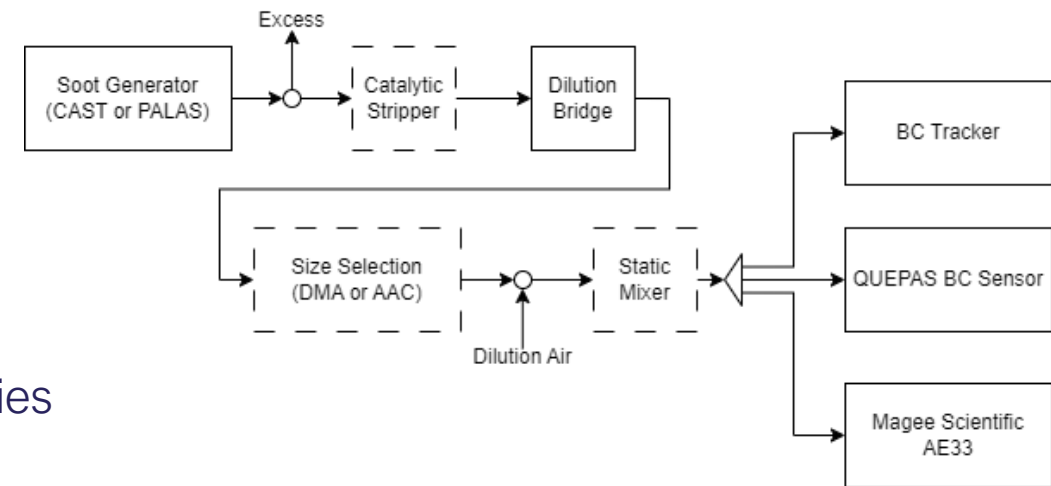
# Roadside Point Sampling (PS) Setup





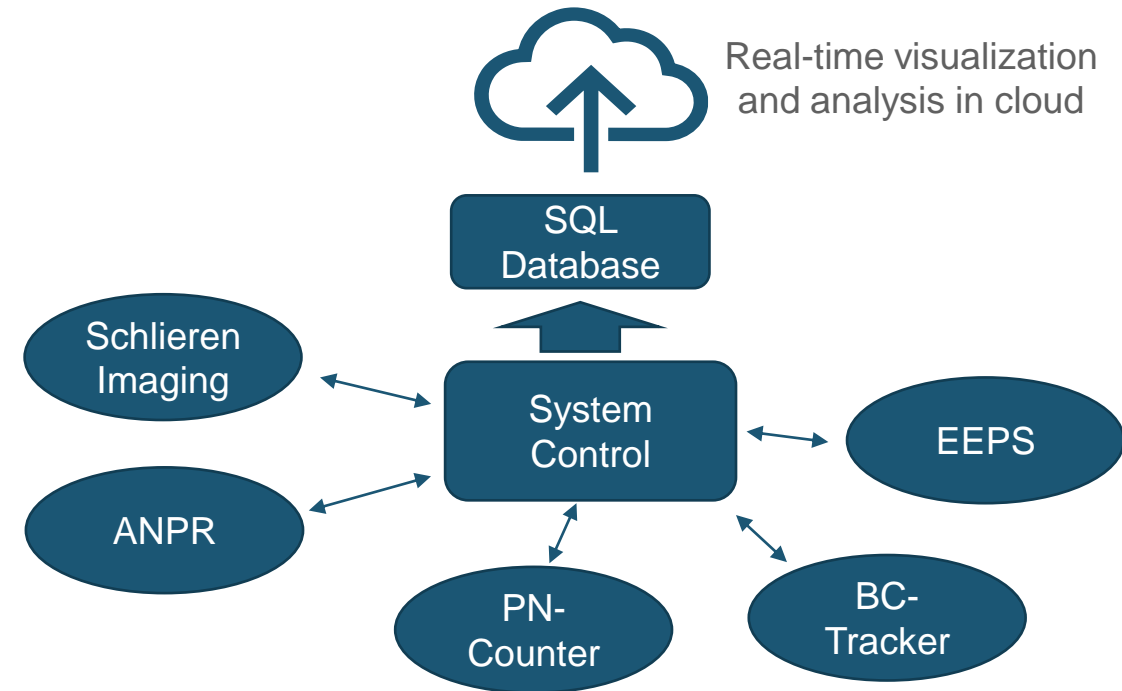
# Device Validation Campaign

- In-lab sensor calibration
  - Calibration of black-carbon sensors for different EC/OC ratios
  - Particle number (PN) - Sensor calibration
  - CO<sub>2</sub>-sensor and NO<sub>x</sub>-sensor factory calibrated
  - Engine exhaust particle sizer (EEPS) calibrated
- Point Sampling Exercise
  - Around 150 passes of L-vehicles with different categories
  - Validation of all sensors with PS



# Data Management

- Point sampling data management
  - PS shelter equipped with central system control
  - Instrument time alignment
  - Sampling time correction
  - Data logging and storage → local SQL database
- Optional cloud uplink
  - Link SQL database to cloud
  - Real-time visualization hub
    - publicly visible data stream (e.g. post link on webpage)
    - log-in protected data stream (e.g. for project partners)
    - log-in protected alarm page (e.g. for authorities)
  - Cloud real-time data analysis possible – option for future campaigns



# Data Analysis

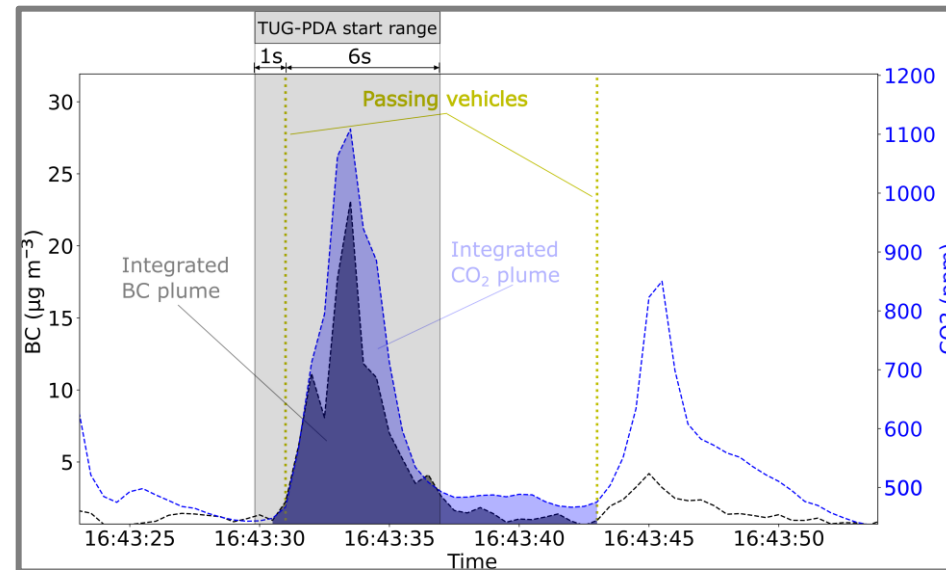
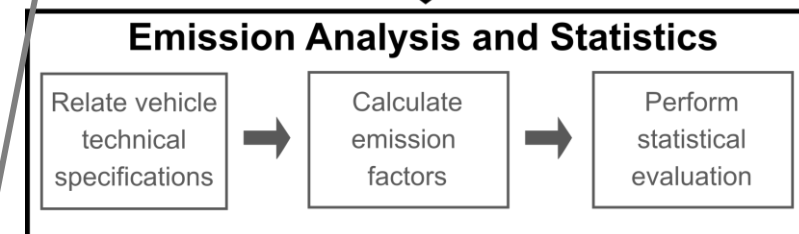
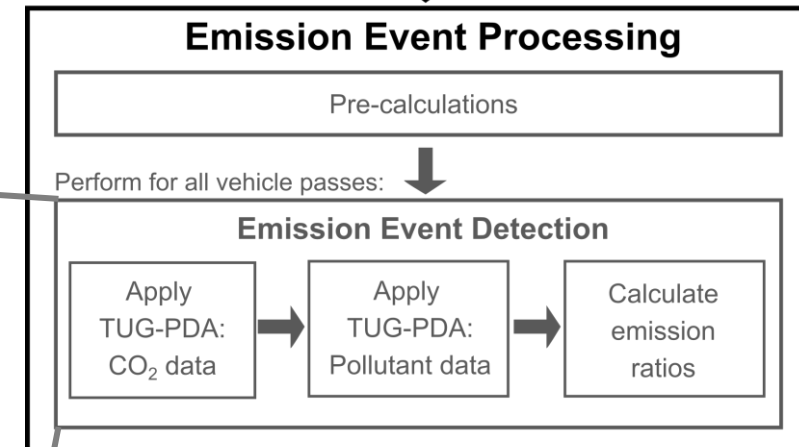
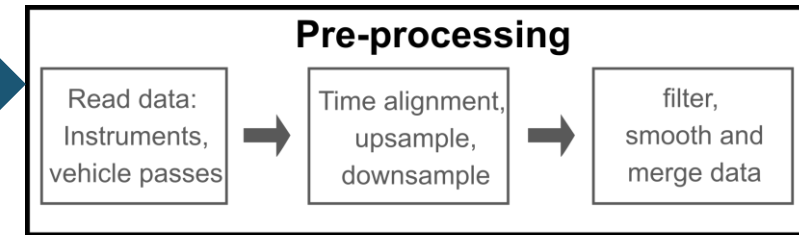
- Based on [Knoll et al. Large-scale automated emission measurement of individual vehicles with point sampling. Pre-print. EGU sphere. 2023.] – approach for CARES data

- Automated post-processing

- Peak detection
- Alignment
- Pollution data
- Obtain Efs

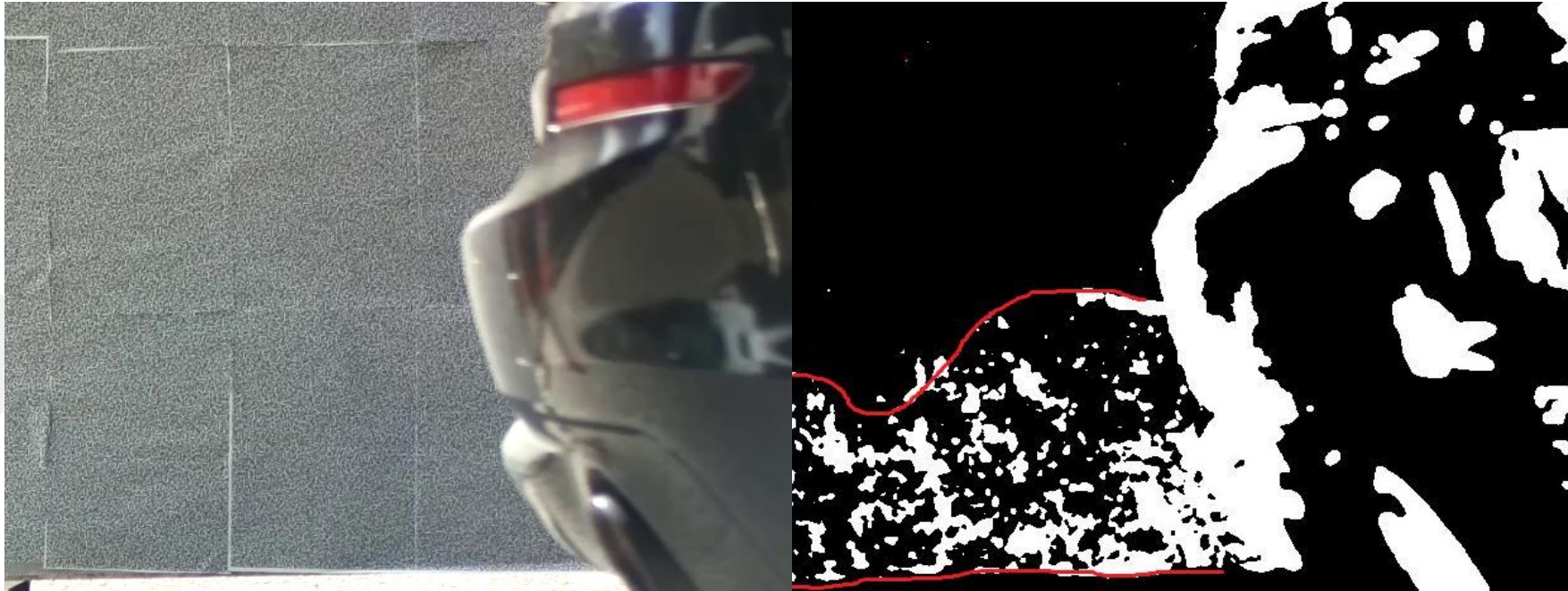
- Emission Factors  
(Emission Ratio ER)

$$ER = \frac{\int_{t_1}^{t_2} ([P]_t - [P]_{t_0}) dt}{\int_{t_1}^{t_2} ([CO_2]_t - [CO_2]_{t_0}) dt}$$



# Schlieren Imaging Technique

Car – Leuven – Donkerstraat 37 - 2024-05-13 15:41:28



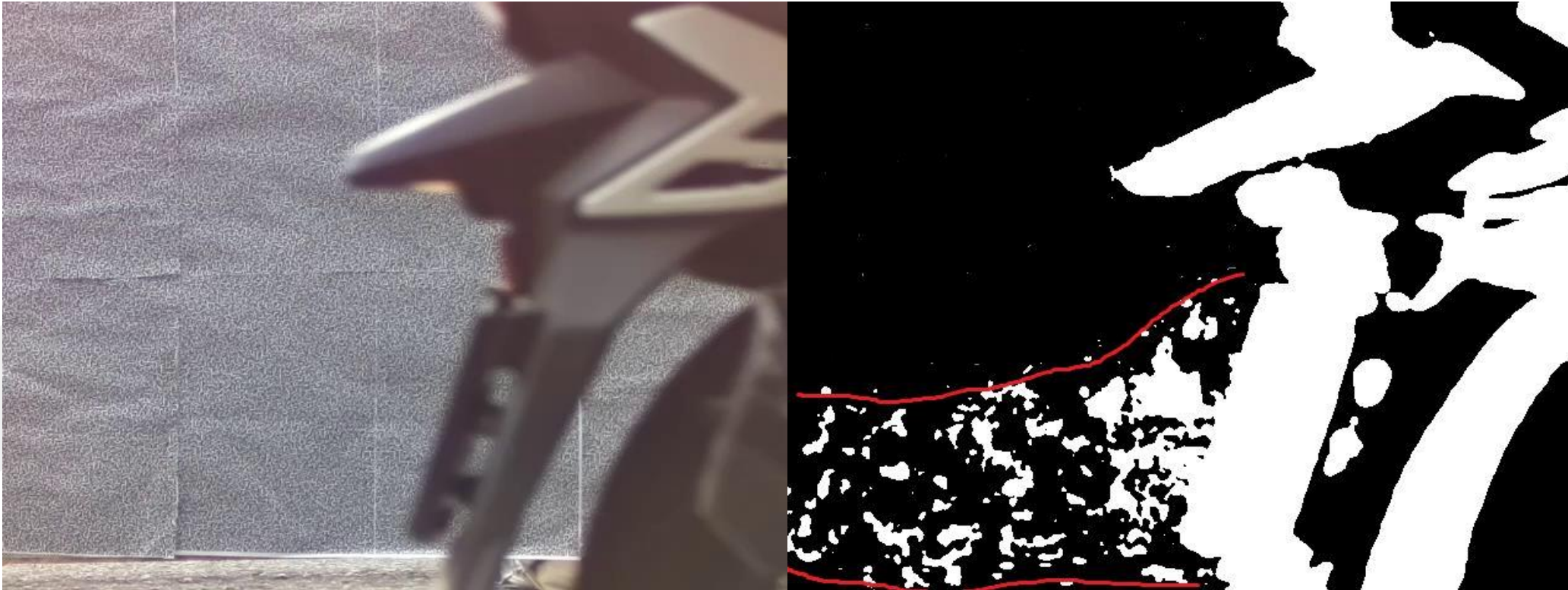
Original image

Schlieren image



# Schlieren Imaging Technique

Scooter – Leuven – Donkerstraat 37 - 2024-05-13 17:20:41



Original image

Schlieren image

# Schlieren Imaging Technique

Heavy Bike – Leuven – Donkerstraat 37 - 2024-05-13 16:14:25



Original image

Schlieren image

# Conclusion

- Point sampling setup with all the sensing devices have been setup in Leuven
- More than 100 L-vehicles have been tested in Leuven in last two days
- Detection of high emitters will be done after post processing of data from all the devices
- Detection of high emitters in real time by PS in general possible when thresholds are defined, possibly by combining the analyzed LENS emission data



*Thank you!*

# Contacts

Hafiz Hashim Imtiaz  
Hafiz.Imtiaz@tugraz.at

Martin Kupper  
Martin.kupper@tugraz.at

Alexander Bergmann  
Alexander.bergmann@tugraz.at

**Disclaimer**

*Funded by the European Union. Views and opinions expressed are however those of the author(s) only and do not necessarily reflect those of the European Union or the granting authority. Neither the European Union nor the granting authority can be held responsible for them.*

*Any communication or dissemination activity related to the action must use factually accurate information.*



This project has received funding from the European Union's Horizon Europe research and innovation programme under grant agreement No 101056777

# Colour palette



## RGB

102/98/255

0/159/227

40/35/93

81/192/72

225/225/225

## HEX

6662ff

009fe3

28235d

51c048

E1E1E1